

# Panel Data Econometrics (PhD) Non-linear Static & Dynamic Models

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July 4, 2012

# Maximum Likelihood Estimation Recap

## Introduction

- ▶ ML method assumes knowledge of the entire distribution, not just of a number of its moments as in GMM method
- ▶ If these distributional assumptions are correct, the ML estimator, is under weak regularity conditions, consistent and asymptotically normal.
- ▶ It is also asymptotically efficient since it fully exploits the assumptions about the distribution.
- ▶ Starting assumptions of ML:
  - ▶ The conditional distribution of an observed phenomenon is known, except for a finite number of unknown parameters.
  - ▶ These parameters will be estimated by taking those values for them that give the observed values the highest probability, the highest likelihood.
  - ▶ It provides an approach of estimating a set of parameters characterizing a distribution, if we know, or assume we know, the form of this distribution

# Maximum Likelihood Estimation Recap

## Introduction

### Example -1

- ▶ Consider a large pool of balls filled with red and yellow balls
- ▶ One could be interested in the fraction  $p$  of red balls in this pool
- ▶ Take random sample of  $N$  balls only
- ▶ Let  $y_i = 1$  if ball  $i$  is red and  $y_i = 0$  otherwise
- ▶ Thus,  $P\{y_i = 1\} = p$
- ▶ Suppose the pool of ball contains  $N_1 = \sum_{i=1}^N y_i$  red and  $N - N_1$  yellow balls

# Maximum Likelihood Estimation Recap

## Introduction Cont.

### Example -1 Cont.

- ▶ The likelihood (probability) of obtaining such a sample is given by:

$$P\{N_1 \text{ red balls}, N - N_1 \text{ yellow balls}\} = p^{N_1}(1 - p)^{N - N_1} \quad (1)$$

- ▶ Equation 1 is what is called the **Likelihood Function** and it is a function of the unknown parameter  $p$ .
- ▶ In ML estimation, we choose a value for  $p$  such that the likelihood function is maximal, and obtain  $\hat{p}$ .
- ▶ The conventional practice is to maximize the log-likelihood, which is a simple monotonic transformation of equation [1] (for computational convenience)

$$\log L(p) = N_1 \log(p) + (N - N_1) \log(1 - p) \quad (2)$$

# Maximum Likelihood Estimation Recap

## Introduction Cont.

### Example -1 Cont.

- ▶ FOC to maximize [1]:

$$\frac{d \log L(p)}{dp} = \frac{N_1}{p} - \frac{N - N_1}{1 - p} = 0 \quad (3)$$

- ▶ Solving [3] for  $p$  gives the ML estimator  $\hat{p} = N_1/N$
- ▶ It corresponds to the sample proportion of red balls, and most likely to your best guess for  $p$  based on the sample drawn
- ▶ SOC:

$$\frac{d^2 \log L(p)}{dp^2} = \frac{N_1}{p^2} - \frac{N - N_1}{(1 - p)^2} < 0 \quad (4)$$

- ▶ Indicating that we indeed have a maximum
- ▶ Another example:

# Maximum Likelihood Estimation Recap

## Introduction Cont.

### Example 2.

- ▶ Consider the simple regression model

$$y_i = \beta_1 + \beta_2 x_i + \varepsilon_i \quad (5)$$

- ▶ Keep assumptions [A1][A4]
- ▶ The assumptions imply that  $E\{y_i|x_i\} = \beta_1 + \beta_2 x_i$  &  $V\{y_i|x_i\} = \sigma^2$
- ▶ To estimate the above model, we need to impose distributional assumption on  $\varepsilon$ , the most common being assumption [A5] (normal dist.)

# Maximum Likelihood Estimation Recap

## Introduction Cont.

### Example 2.

- ▶ The contribution of the  $i^{\text{th}}$  observation to the likelihood function is the value of the density function at the observed point  $y_i$ . Which, for a normal distribution yields,

$$f(y_i|x_i; \beta, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left\{-\frac{1}{2} \frac{(y_i - \beta_1 - \beta_2 x_i)^2}{\sigma^2}\right\} \quad (6)$$

- ▶ **Note:**  $y_i$  has a continuous distribution, hence the likelihood of observing a particular outcome  $y$  for  $y_i$  is zero for any  $y$
- ▶ Where  $\beta = (\beta_1, \beta_2)$
- ▶ The joint density of  $(y_1, \dots, y_N)$  conditional on  $X = (x_1, \dots, x_N)'$  is stated as

$$f(y_1, \dots, y_N | X; \beta, \sigma^2) = \prod_{i=1}^N f(y_i | x_i; \beta, \sigma^2) = \left(\frac{1}{\sqrt{2\pi\sigma^2}}\right)^N \prod_{i=1}^N \exp\left\{-\frac{1}{2} \frac{(y_i - \beta_1 - \beta_2 x_i)^2}{\sigma^2}\right\}$$

# Maximum Likelihood Estimation Recap

## Introduction Cont.

### Example 2. Cont.

- ▶ The likelihood function and the joint density function of  $y_1, \dots, y_N$  are similar except the fact that the former is considered as a function of the unknown parameters  $\beta, \sigma^2$
- ▶ The LL function is given by

$$\log L(\beta, \sigma^2) = -\frac{N}{2} \log(2\pi\sigma^2) - \frac{1}{2} \sum_{i=1}^N \frac{(y_i - \beta_1 - \beta_2 x_i)^2}{\sigma^2} \quad (8)$$

- ▶ Maximizing (8) w.r.t  $\beta_1$  &  $\beta_2$  corresponds to minimizing the residual sum of squares  $S(\beta)$ , as shown in OLS. Do you see why?



# Maximum Likelihood Estimation Recap

## Introduction Cont.

### Example 2. Cont.

- ▶ Meaning that the ML estimators of  $\beta_1$  &  $\beta_2$  are identical to the OLS estimators!
- ▶ Denote these estimators by  $\hat{\beta}_1$  and  $\hat{\beta}_2$ , and define the residuals  $e_i = y_i - \hat{\beta}_1 - \hat{\beta}_2 x_i$  and maximize (8) w.r.t  $\sigma^2$ . FOC:

$$-\frac{N}{2} \frac{2\pi}{2\pi\sigma^2} + \frac{1}{2} \sum_{i=1}^N \frac{e_i^2}{\sigma^4} = 0 \quad (9)$$

- ▶ Solve(9) for  $\sigma^2$  to get the ML estimator for  $\sigma^2$  given by

$$\hat{\sigma}^2 = \frac{1}{N} \sum_{i=1}^N e_i^2 \quad (10)$$

# Maximum Likelihood Estimation Recap

## Introduction Cont.

### Example 2. Cont.

- ▶ Note that however this estimator is consistent but not unbiased (a small sample problem) as the estimator in OLS which was given by

$$s^2 = \frac{1}{N - K} \sum_{i=1}^N e_i^2 \quad (11)$$

- ▶ In many cases, the ML estimator cannot be shown to be unbiased (unknown small sample properties)
- ▶ Its use generally is defended based on asymptotic grounds
- ▶ Analytical solution of the ML estimator is also difficult in many cases except in some general cases as shown above

# Maximum Likelihood Estimation Recap

## Specification Tests

- ▶ Three types of tests
  1. The Wald test: pretty much in line with  $t$  and  $F$  tests
  2. The likelihood ratio test: used to compare two alternative nested models
  3. The lagrange multiplier test: used to test restrictions imposed in estimation

# Cross-sectional Binary Choice Models

## Recap

- ▶ Used to model phenomena that are of discrete nature
  - ▶ Do married women participate in the labor force?
  - ▶ Which sections of society are poor?
  - ▶ What are the determinants of an agricultural technology adoption?
- ▶ For such kinds of models, OLS is generally inappropriate - we rather use binary choice models
- ▶ Mostly (although not exclusively) the problems analyzed are micro-economic nature

# Cross-sectional Binary Choice Models

## Recap Cont.

- ▶ Suppose we want to study the impact of income (assumed as the only variable here) on the probability of owning a car:

$$y_i = \beta_1 + \beta_2 x_{i2} + \varepsilon_i = x_i' \beta + \varepsilon_i \quad (12)$$

- ▶ Where,  $y_i = 1$  if family  $i$  owns a car, 0 if family  $i$  does not own a car
- ▶  $x_i = (x_{i1}, x_{i2})'$
- ▶ The standard assumptions:

$$E\{\varepsilon_i | x_i\} = 0 \quad \text{such that} \quad E\{y_i | x_i\} = x_i' \beta \implies \quad (13)$$

$$E\{y_i | x_i\} = 1.P\{y_i = 1 | x_i\} + 0.P\{y_i = 0 | x_i\} \quad (14)$$

$$= 1.P\{y_i = 1 | x_i\} = x_i' \beta \quad (15)$$

# Cross-sectional Binary Choice Models

## Recap Cont.

- ▶ Thus, the linear model implies that  $x_i'\beta$  is a probability and should therefore lie between 0& 1.
- ▶ This is only possible if the  $x_i$  values are bounded and if certain restrictions on  $\beta$  are satisfied.
  - ▶ Hard to achieve this in practice
- ▶ Another fundamental problem:
  - ▶  $\varepsilon_i$  in equation [1] has a highly non-normal distribution and suffers from heteroscedasticity
  - ▶ Because  $y_i$  has only two possible outcomes, so does the error term for a given value of  $x_i$
- ▶ The distribution of  $\varepsilon_i$  can be summarized as:

# Cross-sectional Binary Choice Models

Recap Cont.



$$P\{\varepsilon_i = -x_i'\beta|x_i\} = P\{y_i = 0|x_i\} = 1 - x_i'\beta \quad (16)$$

$$P\{\varepsilon_i = 1 - x_i'\beta|x_i\} = P\{y_i = 1|x_i\} = x_i'\beta \quad (17)$$

- ▶ This implies that the variance of the error term is not constant but dependent upon the explanatory variables

$$V\{\varepsilon_i|x_i\} = x_i'\beta(1 - x_i'\beta) \quad (18)$$

# Cross-sectional Binary Choice Models

## Recap Cont.

- ▶ We therefore use binary choice models (or univariate dichotomous models)
- ▶ Describe the probability  $y_i = 1$  directly (but derived from an underlying latent variable model (see next pages))
- ▶ The general formulation is:

$$P\{y_i = 1|x_i\} = G(x_i, \beta) \quad (19)$$

for some function  $G(\cdot)$

- ▶ Equation [8] says that the probability of having  $y_i = 1$  depends on  $x_i$
- ▶ But, clearly,  $G(\cdot)$  should take on values in the interval  $[0, 1]$  only
- ▶ Usually, we assume:

$$G(x_i, \beta) = F(x_i' \beta) \quad (20)$$



# Cross-sectional Binary Choice Models

Recap Cont.

- ▶ Common choices of  $F$  are the standard normal distribution

$$F(x'\beta) = \Phi(x'\beta) = \int_{-\infty}^{x'\beta} \Phi(z) dz, \quad (21)$$

giving rise to the so-called **Probit Model**, and the standard logistic function given by:

$$L(x'\beta) = \frac{e^{x'\beta}}{1 + e^{x'\beta}} \quad (22)$$

leading to the **Logit Model**

# Cross-sectional Binary Choice Models

Recap Cont.

- ▶ A third option is a uniform distribution over the interval  $[0,1]$  with distribution function:

$$F(x'\beta) = 0, x'\beta < 0; \quad (23)$$

$$F(x'\beta) = x'\beta, 0 \leq x'\beta \leq 1; \quad (24)$$

$$F(x'\beta) = 1, x'\beta > 1. \quad (25)$$

- ▶ Leading to what is called the **Linear Probability Model** pretty similar with [12], except that the probabilities are set to 0 or 1 if  $x'_i\beta$  exceeds the lower upper limit respectively.

# Cross-sectional Binary Choice Models

## Recap Cont.

- ▶ Probit and logit are more common on applied work.
- ▶ Both the standard normal and the standard logistic random variable have an expectation of zero, while the latter has a variance of  $\pi^2/3$  instead of 1.
- ▶ Correcting for the scaling difference would give similar results
- ▶ Apart from their signs, the coefficients in these binary choice models are not easy to interpret directly
- ▶ One needs to compute the marginal effects of changes in the explanatory variables

# Cross-sectional Binary Choice Models

## Recap Cont.

- ▶ For a continuous explanatory variable,  $x_{ik}$ , say the marginal effect is defined as the partial derivative of the probability that  $y_i$  equals one.
- ▶ For the three models above, we obtain

$$\frac{\partial \Phi(x'_i \beta)}{\partial x_{ik}} = \phi(x'_i \beta) \beta_k; \quad (26)$$

$$\frac{\partial L(x'_i \beta)}{\partial x_{ik}} = \frac{e^{x'_i \beta}}{(1 + e^{x'_i \beta})} \beta_k \quad (27)$$

$$\frac{\partial (x'_i \beta)}{\partial x_{ik}} = \beta_k; \text{ (or } 0) \quad (28)$$

# Cross-sectional Binary Choice Models

## Recap Cont.

- ▶ MEs are typically computed for the "average" observation, replacing  $x_i$  in the previous expressions with the sample averages.
- ▶ For the logit model, re-write [19] as

$$\log \frac{p_i}{1 - p_i} = x_i' \beta, \quad (29)$$

where  $p_i = P\{y_i = 1|x_i\}$  is the probability of observing outcome 1.

- ▶ The lhs expression is known as the "log odds ratio"
- ▶ For example, an odds ratio of 3 mean that the odds of  $y_i = 1$  are 3 times those of  $y_i = 0$
- ▶ The  $\beta$  coefficients therefore can be interpreted as describing the effect upon the odds ratio
- ▶ If  $\beta_k = 0.1$ , a one-unit increase of  $x_{ik}$  increases the odds ratio by about 10% (*ceteris paribus*)

# Cross-sectional Binary Choice Models

## Recap Cont.

### Estimation

- ▶ Very often binary choice models are derived from underlying behavioral model - following the latent model approach.

$$y^* = x_i' \beta + \epsilon_i \quad (30)$$

- ▶  $y^*$  is referred to as the latent variable because it is unobserved
- ▶ Assume a probability model of working where a person chooses to work if the utility difference exceeds a certain threshold level
- ▶ Thus, one observes  $y_i = 1$  (working) if and only if  $y_i^* > 0$ , and  $y_i = 0$  (not working) otherwise.
- ▶ Hence,

$$P\{y_i = 1\} = P\{y_i^* > 0\} = P\{x_i' \beta + \epsilon_i > 0\} = P\{-\epsilon_i \leq x_i' \beta\} = F(x_i' \beta) \quad (31)$$

Where  $F$  denotes the distribution function of  $-\epsilon_i$

# Cross-sectional Binary Choice Models

## Recap Cont.

### Estimation

- ▶ The likelihood contribution of observation  $i$  with  $y_i = 1$  is given by  $P\{y_i = 1|x_i\}$  as a function of  $\beta$ . We do the same for  $y_i = 0$
- ▶ We can write the likelihood function to be maximized for the entire sample as

$$L(\beta) = \prod_{i=1}^N P\{y_i = 1|x_i; \beta\}^{y_i} P\{y_i = 0|x_i; \beta\}^{1-y_i} \quad (32)$$

and the corresponding loglikelihood function (which is convenient to work with) will be given by

$$\log L(\beta) = \sum_{i=1}^N y_i \log F(x_i' \beta) + \sum_{i=1}^N (1 - y_i) \log(1 - F(x_i' \beta)). \quad (33)$$

# Non-linear Panel Data Models

## Panel Binary Choice Models

- ▶ A binary choice model is formulated in terms of an underlying latent model

$$y_{it}^* = x_{it}'\beta + \alpha_i + u_{it} \quad (34)$$

- ▶ Where:

$$y_{it} = \begin{cases} 1 & \text{if } y_{it}^* > 0; \\ 0, & \text{otherwise.} \end{cases} \quad (35)$$

- ▶ Assume  $u_{it}$  has a symmetric distribution with distribution function  $F(\cdot)$ , *i.i.d* across  $i$  &  $t$  and independent of all  $x_{is}$
- ▶ The presence of  $\alpha_i$  complicates estimation even when one treats them as fixed unknown parameters, and as random error terms.
- ▶ Treating as fixed unknown = including N dummy variables.

Hence:

$$\log L(\beta, \alpha_1, \dots, \alpha_N) = \sum_{it} y_{it} \log F(\alpha_i + x_{it}'\beta) + \sum_{it} (1 - y_{it}) \log [1 - F(\alpha_i + x_{it}'\beta)]$$



# Non-linear Models

## Panel Binary Choice Models Cont.

- ▶ Max w.r.t  $\beta$  &  $\alpha_i (i = 1, \dots, N)$  will result in consistent estimates only when  $T \sim \infty$
- ▶ For fixed  $T$  &  $N \sim \infty$ , the estimators are inconsistent!
- ▶ Why? Due to what is called "incidental parameter" problem
  - ▶ For fixed  $T$ , the number of parameters grow with  $N$
  - ▶  $\alpha_i$  can be estimated consistently only when  $T \sim \infty$  (i.e the number of observations for individual  $i$  grows)
  - ▶ The inconsistency of  $\hat{\alpha}_i$  for fixed  $T$  will carry over to the estimator for  $\beta$
- ▶ Why was the incidental parameter problem not an issue in the linear FE model?

# Non-linear Models

## Panel Binary Choice Models Cont.

- ▶ Alternative strategy: conditional maximum likelihood estimator
- ▶ Considers the likelihood function conditional upon a set of statistics  $t_i$  that are sufficient for  $\alpha_i$ 
  - ▶ Conditional upon  $t_i$  an individual's likelihood contribution no longer depends upon  $\alpha_i$  but still depends upon the other parameters  $\beta$
- ▶ In the panel data binary choice model, the existence of a sufficient statistic depends upon the functional form of  $F$ , i.e., depends upon the distribution of  $u_{it}$
- ▶ Let the joint density or probability mass function of  $y_{i1}, \dots, y_{iT} = f(y_{i1}, \dots, y_{iT} | \alpha_i, \beta)$
- ▶ If a sufficient statistic  $t_i$  exists  $\Rightarrow$ 

$$f(y_{i1}, \dots, y_{iT} | t_i, \alpha_i, \beta) = f(y_{i1}, \dots, y_{iT} | t_i, \beta)$$
- ▶ Maximize the conditional likelihood function based upon  $f(y_{i1}, \dots, y_{iT} | t_i, \beta)$  to get a consistent estimator of  $\beta$

# Non-linear Models

## Panel Binary Choice Models Cont.

- ▶ Takes  $t_i = \bar{y}_i$  as a sufficient statistic for  $\alpha_i$  and applies CML
- ▶ Note: The conditional distribution of  $y_{i1}, \dots, y_{iT}$  is degenerate if  $t_i = 0$  or  $t_i = 1$
- ▶ Such individuals do not contribute to the CL and should be discarded in estimation
- ▶ Only individuals that change status at least once are relevant for estimating  $\beta$
- ▶ Consider the case where  $T = 2$
- ▶ By conditioning upon  $t_i = 1/2$ , we restrict the sample to the observation for which  $y_{it}$  changes.  $(0, 1)$  &  $(1, 0)$  will be the two possible outcomes

# Non-linear Models

## Panel Binary Choice Models - FE Logit

- ▶ The conditional probability of the first outcome is

$$P\{(0,1)|t_i = 1/2, \alpha_i, \beta\} = \frac{P\{(0,1)|\alpha_i, \beta\}}{P\{(0,1)|\alpha_i, \beta\} + P\{(1,0)|\alpha_i, \beta\}} \quad (37)$$

Making use of

$$P\{(0,1)|\alpha_i, \beta\} = P\{y_{i1} = 0|\alpha_i, \beta\}P\{y_{i2} = 1|\alpha_i, \beta\} \quad (38)$$

and

$$P\{y_{i2} = 1|\alpha_i, \beta\} = \frac{\exp\{\alpha_i + x'_{i2}\beta\}}{1 + \exp\{\alpha_i + x'_{i2}\beta\}} \quad (39)$$

- ▶ Thus the conditional probability is given by

$$P\{(0,1)|t_i = 1/2, \alpha_i, \beta\} = \frac{\exp\{(x_{i2} - x_{i1})'\beta\}}{1 + \exp\{(x_{i2} - x_{i1})'\beta\}} \quad (40)$$

- ▶ And it does not depend on  $\alpha_i$  any more

# Non-linear Models

## Panel Binary Choice Models FE Logit Cont.

- ▶ In a similar fashion:

$$P\{(1,0)|t_i = 1/2, \alpha_i, \beta\} = \frac{1}{1 + \exp\{(x_{i2} - x_{i1})'\beta\}} \quad (41)$$

- ▶ The conditional distribution of  $(y_{i1}, y_{i2})$ , given  $t_i$  &  $\alpha_i$  is independent of the individual specific effects
- ▶ Thus, for  $T = 2$ , estimation is possible using a standard logit with  $x_{i2} - x_{i1}$  as explanatory variables and the change in  $y_{it}$  as the endogenous event (1 for positive change, 0 for a negative one)
- ▶ Conditioning upon  $t_i = 1/2 \Rightarrow$  first differencing (or within transforming) as in the case of linear panel data models
- ▶ The principle is straightforward in the case of larger  $T$ .
- ▶ The CML approach is also extendable to the multinomial logit model

# Non-linear Models

## Panel Binary Choice Models - RE Probit

- ▶ Follow the latent variable specification

$$y_{it}^* = x_{it}'\beta + \varepsilon_{it} \quad (42)$$

- ▶ Where:

$$y_{it} = \begin{cases} 1 & \text{if } y_{it}^* > 0; \\ 0, & \text{otherwise.} \end{cases} \quad (43)$$

$$\varepsilon_{it} \sim (0, 1) \quad (44)$$

$$E\{\varepsilon_{it}, x_{it}\} = 0 \quad (45)$$

# Non-linear Models

## Panel Binary Choice Models - RE Probit Cont.

- ▶ To estimate  $\beta$  by ML, one needs an assumption about the joint distribution of  $(\varepsilon_{i1}, \dots, \varepsilon_{iT})$
- ▶ If we assume that the  $\varepsilon_{it}$  are independent,  $\implies f(y_{i1}, \dots, y_{iT}, \beta) = \prod_t f(y_{it}, \beta)$ , which involves  $T$  one-dimensional integrals only (as in the cross-sectional case)
- ▶ Assume:

$$\varepsilon = \alpha_i + u_{it} \quad (46)$$

$$E\{u_{it}, u_{is}\} = 0 \quad (47)$$

- ▶ The joint probability will be:

$$f(y_{i1}, \dots, y_{iT} | x_{i1}, \dots, x_{iT}, \beta) = \int_{-\infty}^{\infty} f(y_{i1}, \dots, y_{iT} | x_{i1}, \dots, x_{iT}, \alpha_i, \beta) f(\alpha_i) d\alpha_i \quad (48)$$

# Non-linear Models

## Panel Binary Choice Models - RE Probit Cont.

- ▶ Requires numerical integration over one dimension  $\implies$  feasible to allow for correlation of the composite error term  $\varepsilon_{it}$  (not the  $u_{it}$ )

$$\lambda = \text{Corr}(\varepsilon_{it}, \varepsilon_{is}) = \frac{\sigma_{\alpha}^2}{\sigma_{\alpha}^2 + \sigma_u^2} \quad (49)$$

- ▶ In principle, arbitrary assumptions can be made about distributions of  $\alpha_i$  &  $u_{it}$ , but in practice, not attractive!
- ▶ The most common assumption is the multivariate normal distribution which gives rise to the **Random Effects Probit Model**.
- ▶ Let's see how it works:



# Non-linear Models

## Panel Binary Choice Models - RE Probit Cont.

### ► Assumptions

$$\varepsilon_{it} \sim N(0, 1) \quad (50)$$

- As in the cross-sectional case, the error variance is normalized to 1

$$\text{cov}\{\varepsilon_{it}, \varepsilon_{is}\} = \sigma_\alpha^2, s \neq t \quad (51)$$

►  $\implies$

$$\alpha_i \sim NID(0, \sigma_\alpha^2) \quad (52)$$

$$u_{it} \sim NID(0, 1 - \sigma_\alpha^2) \quad (53)$$

# Non-linear Models

## Panel Binary Choice Models - RE Probit Cont.

- ▶ The Likelihood function is given by:

$$f(y_{it}|x_{it}, \alpha_i, \beta) = \Phi\left(\frac{x'_{it}\beta + \alpha_i}{\sqrt{1 - \sigma_\alpha^2}}\right) \quad \text{if } y_{it} = 1 \quad (54)$$

$$= 1 - \Phi\left(\frac{x'_{it}\beta + \alpha_i}{\sqrt{1 - \sigma_\alpha^2}}\right) \quad \text{if } y_{it} = 0 \quad (55)$$

- ▶ Where  $\Phi$  denotes the CDF of the standard normal distribution
- ▶ The density of  $\alpha_i$  is given by

$$f(\alpha_i) = \frac{1}{\sqrt{2\pi\sigma_\alpha^2}} \exp\left\{-\frac{1}{2} \frac{\alpha_i^2}{\sigma_\alpha^2}\right\} \quad (56)$$

- ▶ The integral in equation [48] can be computed numerically using the Gauss-Hermite quadrature (Butler & Moffitt, 1982)
- ▶ The RE Probit is estimable in a standard software such as Stata

# Non-linear Models

## Panel Binary Choice Models - RE Tobit.

- ▶ The RE Tobit is pretty similar to the RE Probit

$$y_{it}^* = x_{it}'\beta + \alpha_i + u_{it} \quad (57)$$

- ▶ Where:

$$y_{it} = \begin{cases} y_{it}^* & \text{if } y_{it}^* > 0; \\ 0, & \text{otherwise.} \end{cases} \quad (58)$$

- ▶ The standard RE assumptions

$$\alpha_i \sim N(0, \sigma_\alpha) \quad (59)$$

$$u_{it} \sim N(0, \sigma_u) \quad (60)$$

# Non-linear Models

## Panel Binary Choice Models - RE Tobit Cont.



$$E\{x_{it}, \alpha_i\} = 0 \quad (61)$$

$$E\{x_{it}, u_{it}\} = 0 \quad (62)$$

- ▶ The likelihood function is given as:

$$f(y_{i1}, \dots, y_{iT} | x_{i1}, \dots, x_{iT}, \beta) = \int_{-\infty}^{\infty} \prod_t f(y_{it} | x_{it}, \alpha_i, \beta) f(\alpha_i) d\alpha_i, \quad (63)$$

$$f(\alpha_i) = \frac{1}{\sqrt{2\pi\sigma_\alpha^2}} \exp\left\{-\frac{1}{2} \frac{\alpha_i^2}{\sigma_\alpha^2}\right\} \quad (64)$$

# Non-linear Models

## Panel Binary Choice Models - RE Tobit Cont.

- ▶ &

(65)

- ▶ NOte: the later two expressions are similar to the likelihood contributions in the cross-sectional case (the only difference is the inclusion of  $\alpha_i$  in the conditional mean.

# Dynamic Probit Models & The Initial Conditions Problem

## Example - Poverty Persistence

- ▶ A poverty probability model is estimated using a dynamic probit model due to state dependence in poverty
- ▶ State dependence in poverty: An individual (a household) experiencing a poverty spell today is much more likely to experience it again in the future
- ▶ Five possible reasons for true state dependence in poverty
  1. Unwillingness to take-up a new job or continue working when wage is too low
  2. Deterioration of human capital during a spell of unemployment
  3. Social exclusion due to poverty - addiction to drug and alcohol
  4. Accepting social welfare support as a way of living
  5. Inability to engage in marriage or cohabitation - reduce the opportunity of economies of scale

# Dynamic Probit Models & The Initial Conditions Problem

## Example - Poverty Persistence Contd...

- ▶ Let the probability of being poor be specified as

$$p_{it}^* = \gamma p_{it-1} + x'_{it}\beta + \alpha_i + u_{it} \quad (66)$$

- ▶  $(i = 1, \dots, N; t = 2, \dots, T)$ ,
- ▶ where  $p_{it}^*$  is a latent dependent variable;
- ▶  $x_{it}$  is a vector of exogenous explanatory variables,
- ▶  $\alpha_i$  are (unobserved) individual-specific random effects, and
- ▶  $u_{it} \sim N(0, \sigma_u^2)$
- ▶ It is assumed that  $N$  is large but  $T$  is small, which implies that asymptotics depend on  $N$  alone.

# Dynamic Probit Models & The Initial Conditions Problem

## Example - Poverty Persistence Contd...

- ▶  $p_{it}$  is the observed binary outcome variable defined as
- ▶ Even when  $u_{it}$  is serially independent, the composite error term  $v_{it} = \alpha_i + u_{it}$  will be correlated overtime because of  $\alpha_i$
- ▶ The RE specification adopted implies equicorrelation between the  $v_{it}$  in any two periods:

$$\rho = \text{Corr}(v_{it}, v_{is}) = \frac{\sigma_{\alpha}^2}{\sigma_{\alpha}^2 + \sigma_u^2} \quad t, s = 2, \dots, T; t \neq s. \quad (67)$$



# The Initial Conditions Problem

## Example - Poverty Persistence Contd...

- ▶ The standard RE model also assumes  $\alpha_i$  uncorrelated with  $x_{it}$ , but correlation can be allowed following Mundlak (1978) & Chamberlain (1984).
  - ▶ Correlation between  $\alpha_i$  and the observed characteristics can be allowed by assuming a relationship between  $\alpha_i$  and either the time means of the  $x$  variables or a combination of their lags and leads.
  - ▶ E.g  $\alpha_i = \bar{x}_i' a + \zeta_i$  where  $\zeta_i \sim IID(0, \sigma_\zeta^2)$  independent of  $x_{it}$  and  $u_{it}$  for all  $i, t$ .
- ▶  $p$  is a binary variable  $\longrightarrow$  we require normalization
- ▶ A convenient one is that  $\sigma_u^2 = 1$

# The Initial Conditions Problem

## Example - Poverty Persistence Contd...

- ▶ Under the assumption of normality, the transition probability for individual  $i$  at time  $t$  given  $\alpha_i$ , is then given by

$$P[p_{it}|x_{it}, p_{it-1}, \alpha_i] = \Phi[(\gamma p_{it-1} + x'_{it}\beta + \alpha_i)(2p_{it} - 1)], \quad (68)$$

- ▶  $\Phi$  is the cumulative distribution function of the standard normal

# The Initial Conditions Problem

## Example - Poverty Persistence Contd...

### RE Probit

- ▶ Estimation of the model requires an assumption about the initial observations,  $p_{i1}$  and its relationship with  $\alpha_i$ .
- ▶ One option: assume  $p_{i1}$  to be exogenous  $\implies p_{it-1}$  can be incorporated in  $x_{it}$  and estimated using the standard RE probit model.
- ▶ The assumption that  $p_{it-1}$  is exogenous is however a strong assumption because of what is called *the initial conditions problem*
- ▶ The start of the observation period does not coincide with the start of the stochastic process generating households' poverty persistence

# The Initial Conditions Problem

## Example - Poverty Persistence Contd...

### RE Probit

- ▶ Consequently, estimation of (1) by RE will tend to overstate the degree of state dependence,  $\gamma$
- ▶ Thus,  $\alpha$  should be integrated out
- ▶ Three available methods
  - ▶ Heckman's Estimator
  - ▶ Orme Two-Stage Estimator
  - ▶ Wooldridge's Conditional Maximum Likelihood Estimator

# Dynamic Probit Models

## Heckman's Estimator

- ▶ Heckman's (1981) approach starts by specifying a linearized reduced-form equation for the initial value of the latent variable:

$$p_{i1}^* = z_{i1}'\pi + \eta_i \quad (69)$$

- ▶ Where  $z_{i1}$  is a vector of exogenous instruments (for example pre-sample variables) and includes  $x_{i1}$ , and  $\eta_i$  is correlated with  $\alpha_i$ , but uncorrelated with  $u_{it}$  for  $t \geq 2$ .

$$\eta_i = \theta\alpha_i + u_{i1} \quad (70)$$

where  $\theta > 0$ , and  $\alpha_i$  &  $u_{i1}$  are independent of one another.

# Dynamic Probit Models

## Heckman's Estimator

- ▶ We also assume that  $u_{i1}$  satisfies the same distributional assumptions as  $u_{it}$  for  $t = 2, \dots, T$ .
- ▶ One can therefore write the linearized reduced form for the latent variable for the initial period as

$$p_{i1}^* = z'_{i1} \pi + \theta \alpha_i + u_{i1} \quad (71)$$

- ▶ The joint probability of the observed binary sequence for individual  $i$  given  $\alpha_i$ , is thus:

$$\Phi[(z'_{i1} \pi + \theta \alpha_i)(2p_{i1} - 1)] \prod_{t=2}^T \Phi[(\gamma p_{it-1} + x'_{it} \beta + \alpha_i)(2p_{it} - 1)] \quad (72)$$

# Dynamic Probit Models

## Heckman's Estimator

- ▶ For a random sample of households, the likelihood to be maximized is given by

$$\prod_i \int \{ \Phi[(z_i' \pi + \theta \sigma_\alpha \alpha^*)(2p_{it} - 1)] \times \prod_{t=2}^T \Phi[(\gamma p_{it-1} + x_{it}' \beta + \sigma_\alpha \alpha^*)(2p_{it} - 1)] \} dF(\alpha^*) \quad (73)$$

- ▶ Where  $F$  is the distribution function of  $\alpha^* = \alpha / \sigma_\alpha$
- ▶ Under the normalization used,

$$\sigma_\alpha = \sqrt{\rho / (1 - \rho)} \quad (74)$$

- ▶ with  $\alpha$  assumed to be normally distributed, the integral over  $\alpha^*$  can be evaluated using Gaussian-Hermite quadrature

# Dynamic Probit Models

## Orme's Two-Step Estimator

- ▶ Another approach to address the initial conditions problem suggested by Orme (1997, 2001)
- ▶ Write the initial period latent equation as:

$$p_{i1}^* = z_i' \lambda^* + v_{i1}. \quad (75)$$

- ▶ The cause of the initial conditions problem is the correlation between the regressor  $p_{it-1}$  and the unobservable  $\alpha_i$ ,
- ▶ Thus, Orme uses an approximation to substitute  $\alpha_i$  with another unobservable component that is uncorrelated with the initial observation
- ▶ Assume  $(v_{i1}, \alpha_i) \sim BVN(0, 0, \sigma_v^2, \sigma_\alpha^2, r)$

$$\alpha_i | v_{i1} \sim N\left[r \frac{\sigma_\alpha}{\sigma_v}, \sigma_\alpha^2 (1 - r^2)\right] \quad (76)$$



# Dynamic Probit Models

## Orme's Two-Step Estimator Cont

- ▶ One can rewrite:

$$\alpha_i = r \frac{\sigma_\alpha}{\sigma_v} v_{i1} + \sigma_\alpha \sqrt{(1-r^2)} w_i \quad (77)$$

- ▶ Where  $w_i$  is orthogonal to  $v_{i1}$  by construction and distributed as  $N(0,1)$ .
- ▶ Substituting (16) for  $\alpha_i$  in equation (1) yields,

$$p_{it}^* = \gamma p_{it-1} + x'_{it} \beta + \left[ r \frac{\sigma_\alpha}{\sigma_v} v_{i1} + \sigma_\alpha \sqrt{(1-r^2)} w_i \right] + u_{it} \quad (78)$$

- ▶ Equation (17) has two time invariant unobserved components,  $v_{i1}$  and  $w_i$ .
- ▶ Since  $E(w_i | p_{i1}) = 0$ , allowing for the correlation of  $v_{i1}$ , and  $p_{i1}$  addresses the initial conditions problem.

# Dynamic Probit Models

## Orme's Two-Step Estimator Cont

- ▶ Orme shows that Eq(17) and the assumption of BVN imply that,

$$e_i \equiv E(v_{i1} | p_{i1} = (2p_{i1} - 1)\sigma_v \phi(\lambda^* z_i / \sigma_v) / \Phi((2p_{i1} - 1)\lambda^* z_i / \sigma_v), \quad (79)$$

- ▶ Where  $\phi$  and  $\Phi$  are the Normal density and distribution functions, respectively.
- ▶ This is the generalized error from a first period probit equation, analogous to that used in Heckman's sample selection model estimator.
- ▶ Thus, one can estimate Eq(17) as a random-effects probit model with an estimate of  $e_i$  (obtained after the estimation of (17) using a simple probit for the initial period) used in place of  $v_{i1}$ .

# Dynamic Probit Models

## Wooldridge's Conditional Maximum Likelihood (CML) Estimator

- ▶ Proposes an alternative CML estimator that considers the distribution of  $p_2, p_3, \dots, p_T$  conditional on the initial period value  $p_1$  (and exogenous variables)
- ▶ Let the joint density for the observed sequence of the dependent variable ( $p_2, p_3, \dots, p_T | p_1$ ) be written as  $(p_T, p_{T-1}, \dots, p_2 | p_1, x, \alpha)$ .
- ▶ To integrate out  $\alpha_i$ , specify an approximation for its density conditional on  $p_{i1}$
- ▶ In the case of RE probit, the following specification is assumed

$$\alpha_i | p_{i1}, z_i \sim N(\zeta_0 + \zeta_1 p_{i1} + z_i' \zeta, \sigma_a^2) \quad (80)$$

where

$$\alpha_i = \zeta_0 + \zeta_1 p_{i1} + z_i' \zeta + a_i \quad (81)$$

# Dynamic Probit Models

## Wooldridge's Conditional Maximum Likelihood (CML) Estimator Cont

- ▶ in which  $z_i$  includes variables that are correlated with  $\alpha_i$ .
- ▶  $z$  here differs from that in the Heckman specification
- ▶ The trick here is that the correlation between  $p_{i1}$  and  $\alpha$  is handled by the use of Eq(20) which gives rise to  $a_i$  - a new unobservable individual-specific heterogeneity term uncorrelated with  $p_{i1}$
- ▶ Substituting Eq(17) into Eq(1) gives

$$Pr(p_{it} = 1 | a_i, p_{i1}) = \Phi[(x'_{it}\beta + \gamma p_{it-1} + \zeta_1 p_{i1} + z'_i \zeta + a_i)] \quad t = 2, \dots$$

(82)

# Dynamic Probit Models

## Wooldridge's Conditional Maximum Likelihood (CML) Estimator Cont

- ▶ Consequently, the likelihood function for household  $i$  is given by

$$L_i = \int \left\{ \prod_{t=2}^T \Phi[(x'_{it}\beta + \gamma p_{it-1} + \zeta_1 p_{i1} + z'_i \zeta + a)](2p_{it} - 1) \right\} g^*(a) da, \quad (83)$$

where  $g^*(a)$  is the normal probability density function of the new unobservable term  $a_i$ .

# Non-linear Static and Dynamic Models

End of Lecture!

► **Thank You!**